

M-410iB/140H



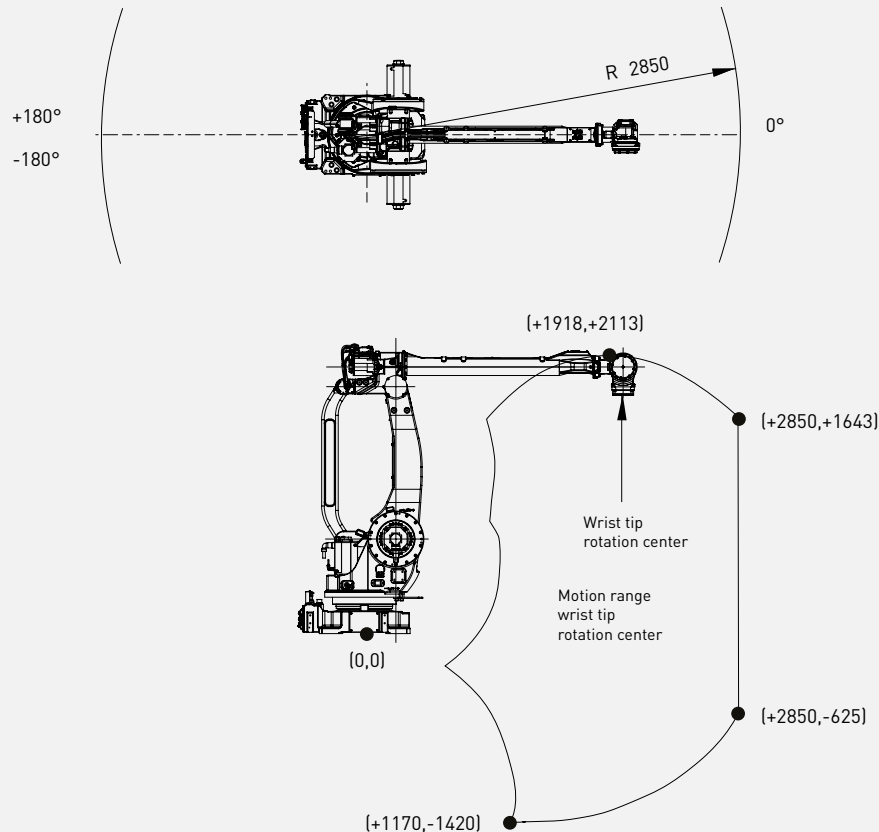
Max. load capacity
at wrist: **140 kg**



Max. reach:
2850 mm

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						J4 Moment/ Inertia (Nm/kgm ²)	J5 Moment/ Inertia (Nm/kgm ²)	J6 Moment/ Inertia (Nm/kgm ²)
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
5	± 0.05	1200	360	155	112	20	720	-	140	115	135	135	420	-	147	53	-

Working range



Robot

	M-410iB/140H
Robot footprint [mm]	806 x 610
Mounting position Floor	●
Mounting position Upside down	-
Mounting position Angle	-

Controller

	R-30iB Plus
Open air cabinet	-
Mate cabinet	-
A-cabinet	●
B-cabinet	○
iPendant Touch	●

Electrical connections

Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	1

Integrated services

Integrated signals on upper arm In/Out	8/8
Integrated air supply	1

Environment

Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45

Protection

Body standard/optional	IP54
Wrist & J3 arm standard/optional	IP54

● standard ○ on request - not available () with hardware and/or software option