

# M-2iA/3S (Hollow wrist)



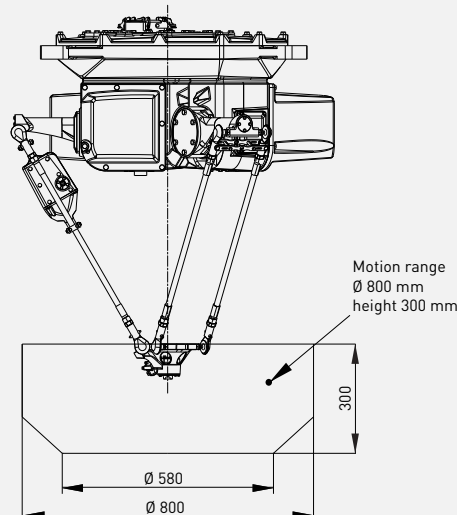
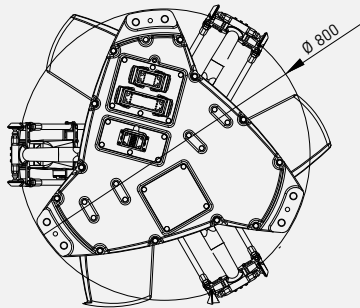
Max. load capacity  
at wrist: **3 kg**



Max. reach:  
**800 mm**

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)							Maximum speed (°/s)							J4 Moment/ Inertia (Nm/kgm <sup>2</sup> )	J5 Moment/ Inertia (Nm/kgm <sup>2</sup> )	J6 Moment/ Inertia (Nm/kgm <sup>2</sup> )
			J1	J2	J3	J4	J5	J6	E1	J1	J2	J3	J4	J5	J6	E1			
4	± 0.1	120	Ø 800 x 300 *3			720	-	-	-	-	-	-	3500	-	-	-		*4	

## Working range



Motion range  
Ø 800 mm  
height 300 mm



### Robot

	M-2iA/3S
Robot footprint [mm]	Ø 800
Mounting position Floor	-
Mounting position Upside down	●
Mounting position Angle	-



### Controller

	R30iB
Open air cabinet	●
Mate cabinet	○
A-cabinet	○
B-cabinet	-
iPendant Touch	●

### Electrical connections

Voltage 50/60Hz 3phase [V]	200-230 *6
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	2.5

### Integrated services

Integrated signals on upper arm In/Out	8/8
Integrated air supply	-

### Environment

Acoustic noise level [dB]	73.7
Ambient temperature [° C]	0-45

### Protection

Body standard/optional	IP67/IP69K
Wrist & J3 arm standard/optional	IP69K

\*3) Ø in mm by height in mm \*4) refer to the wrist load diagramm \*6) transformer required  
 ● standard ○ on request - not available ( ) with hardware and/or software option