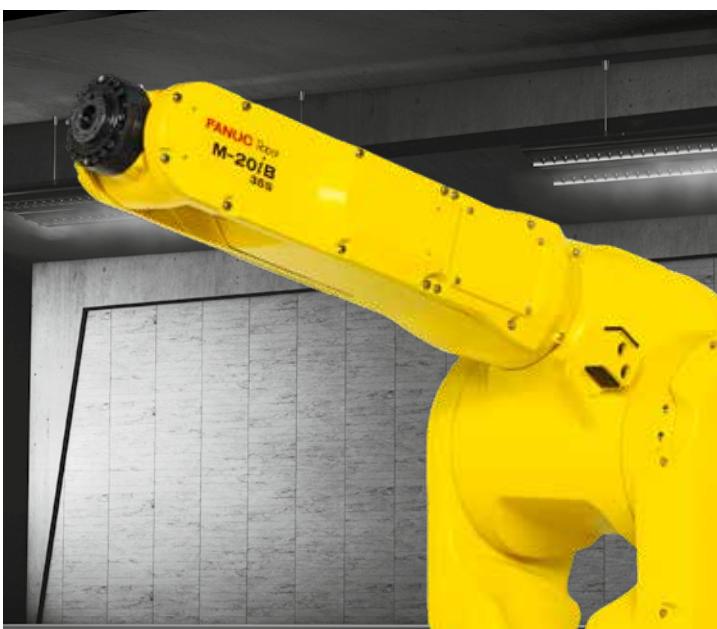


## Compact, strong and fully enclosed



### Flexibility even in narrow spaces

- class leading 35 kg payload capacity
- small wrist design in combination with its payload capacity and inertia, makes it ideal for high payload handling in narrow spaces
- various mounting options increase flexibility of use (floor, angle, ceiling)
- advanced servo technology included
- fully enclosed and smooth design prevents snagging and interference
- full IP67 protection ideal for harsh environments

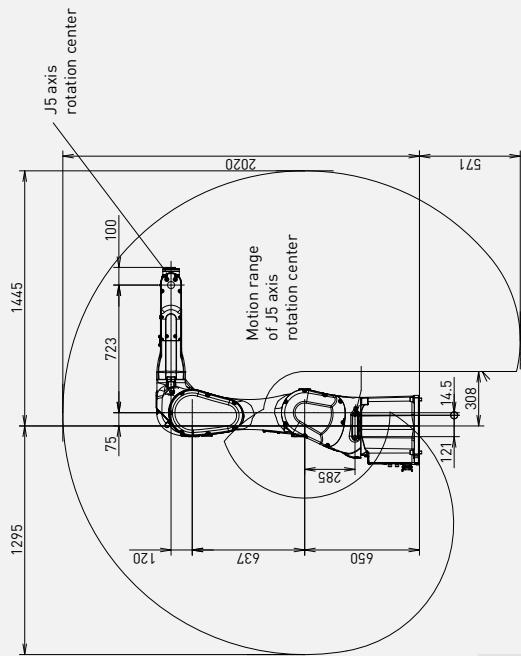
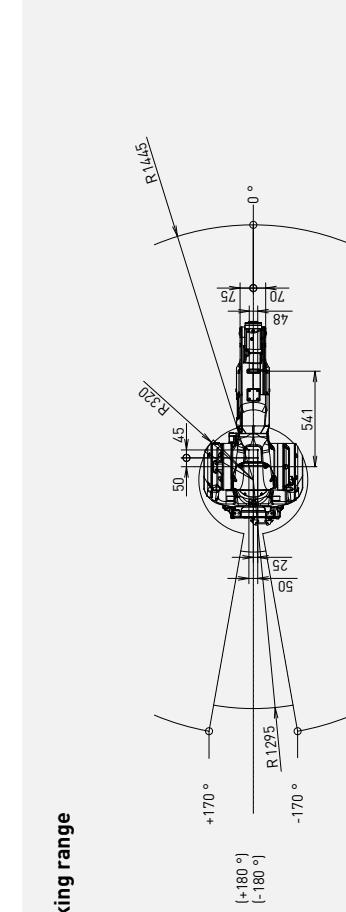
# M-20iB/35S

 Max load capacity at wrist: **35 kg**

 Max. reach: **1445 mm**

Controlled axes	Repeatability (mm)	Mechanical weight [kg]	Motion range [°]						Maximum speed [°/s]						<b>J6 Moment/Inertia (Nm/kgm<sup>2</sup>)</b>	
			J1	J2	J3	J4	J5	E1	J1	J2	J3	J4	J5	E1		
6	± 0.02*	205	340 [360]	240	301,5	400	260	540	-	205	205	260	415	415	880	51 / 2.2

## Working range



Motion range may be restricted according to the mounting angle!

## Robot

- Robot footprint [mm]** 383 x 343
- Mounting position** Floor
- Mounting position** Upside down
- Mounting position Angle**

## Controller

- Open air cabinet** -
- Mate cabinet** -
- A-cabinet** ●
- B-cabinet** ○
- iPendant Touch** ●

## Electrical connections

- Voltage 50/60Hz 3phase M** 380-575
- Voltage 50/60Hz 1phase M** -
- Average power consumption [kW]** 1

## Integrated services

- Integrated signals on upper arm In/Out** 8/2
- Integrated air supply** 1

## Environment

- Acoustic noise level [dB]** < 73.2
- Ambient temperature [° C]** 0-45

- Protection** Body standard/optional
- Wrist & J3 arm standard/optional
- IP67
- IP67