

# The strongest cobot gets a makeover

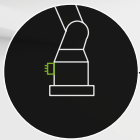
## CR-35iB



**MOUNTING POSITION ON AXIS 3**  
for ancillary equipment



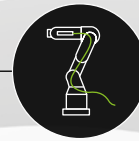
**SPACE SAVING**  
thanks to its compact design



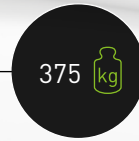
**EASE OF INTEGRATION**  
same installation condition to yellow robot



**35 KG PAYLOAD & 1831 MM REACH**  
for a wider range of applications



**HOLLOW WRIST**  
better cable management for the end of arm tooling



**375 kg**  
**LIGHTER WEIGHT**  
-62% mass compared to the previous model



### Discover the 2<sup>nd</sup> generation of FANUC's collaborative robot

- strongest cobot on the market: 35 kg payload for a wider range of applications
- longest reach on market: 1831 mm reach for maximum utilisation of working areas
- space-saving installation: due to slimmer profile, smaller footprint and pedestal elimination and no need for safety fences
- stop at contact: for safe human-robot collaboration
- Tablet Teach Pendant available as option

# CR-35iB



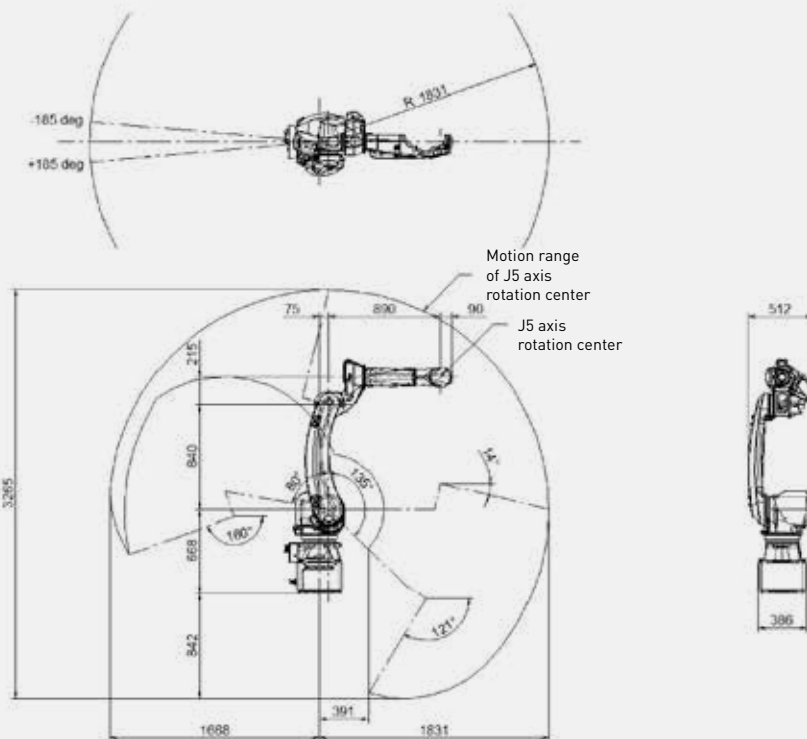
Max. load capacity  
at wrist: **35 kg**



Max. reach:  
**1831 mm**

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (mm/s)	J4 Moment/ Inertia (Nm/kgm <sup>2</sup> )	J5 Moment/ Inertia (Nm/kgm <sup>2</sup> )	J6 Moment/ Inertia (Nm/kgm <sup>2</sup> )
			J1	J2	J3	J4	J5	J6				
6	± 0.03*	386	370	215	338	400	280	900	750*2	110.0/4.00	110.0/4.00	60.0/1.50

## Working range



### Robot

Robot	CR-35iB
Robot footprint [mm]	346x346
Mounting position Floor	•
Mounting position Upside down	-
Mounting position Wall	-



### Controller

Controller	R-30iB Plus
Open air cabinet	-
Mate cabinet	-
A-cabinet	•
B-cabinet	-
iPendant Touch	•
Tablet TP	○

### Electrical connections

Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	1

### Integrated services

Integrated signals on upper arm In/Out	7/5
Integrated air supply	1

### Environment

Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45

### Protection

Body standard/optional	IP54
Wrist & J3 arm standard/optional	IP67

\*1) In case of short distance motion, the speed may not reach the maximum value stated.

\*2) It is necessary to set a motion speed according to risk assessment of system considering pinching with the surroundings.

• standard ○ on request - not available ( ) with hardware and/or software option

\*Based on ISO9283